OVERVIEW OF THE LIGO INSTRUMENT AND THE DATA

Rainer Weiss MIT

Review of the LIGO Open Data Proposal National Science Foundation Arlington, Virginia February 17-18, 2009

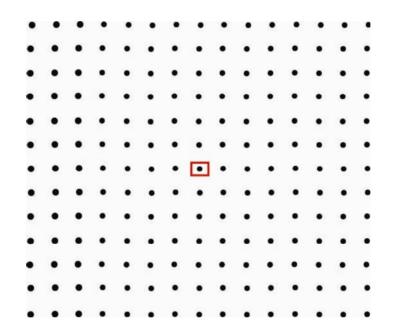
OUTLINE

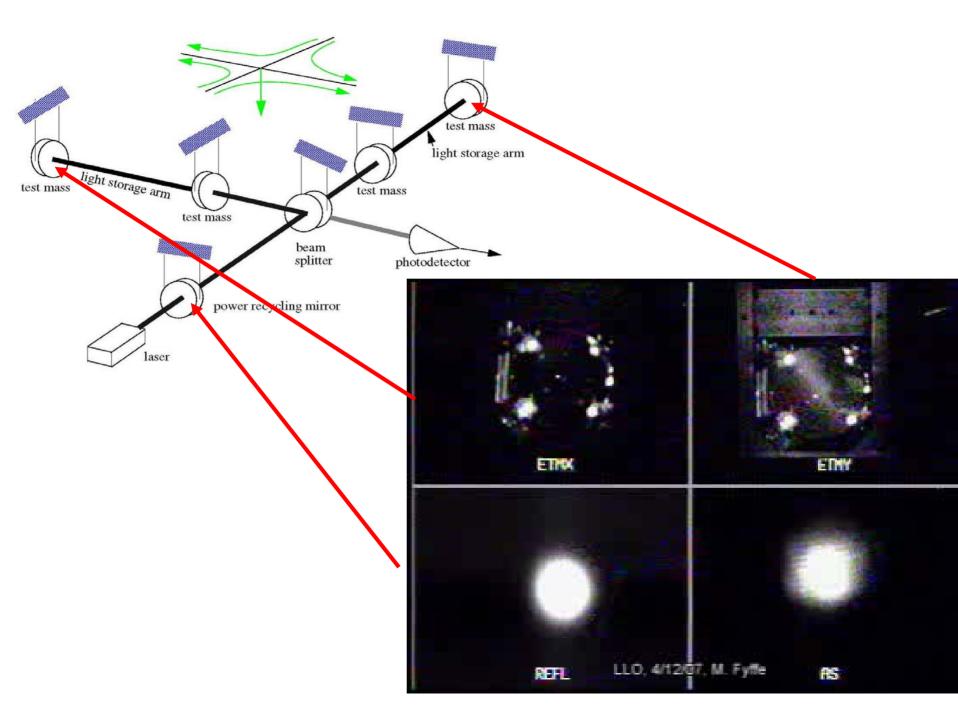
• The instrument: how it works

- The interferometer: subsystems, the variety of signals
- The environmental monitoring system

• The noise

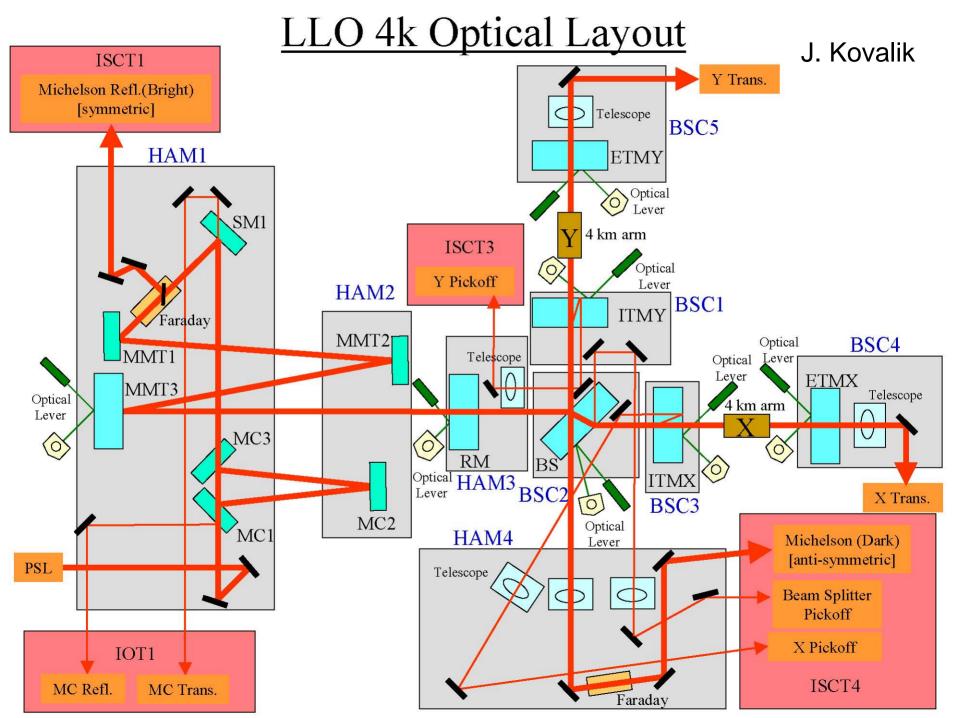
- The fundamental noises: stationary, Gaussian
- The diagnostic technique: stimulus/response/estimate
- The real noise: non-stationary, non-Gaussian
- Experiment styles: why is LIGO data unique
 - searches and measurements
- The nature of the data for a variety of searches
 - Calibration
 - Vetoes and Coincidence
 - Transient sources; compact binary inspiral and unmodeled
 - Steady state sources: pulsars, stochastic background



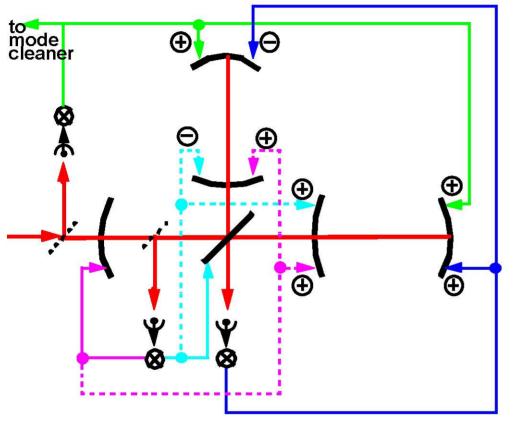


Detector Subsystems Control by feedback

- Length sensing and control
 - Maintain the positions of the optics
- Angular sensing and control
 - Hierarchical alignment strategy
- Laser frequency stabilization
 - Nested frequency control system
 - Relative frequency control
- Laser amplitude stabilization
- Thermal wavefront correction
- Active seismic isolation (at L1 not H1)



Feedback Control Systems



example: cavity length sensing & control topology

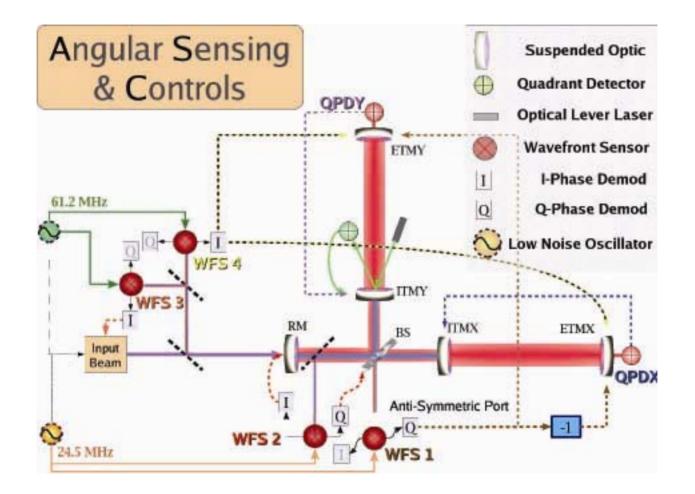
•Array of sensors detects mirror separations, angles

•Signal processing derives stabilizing forces for each mirror, filters noise

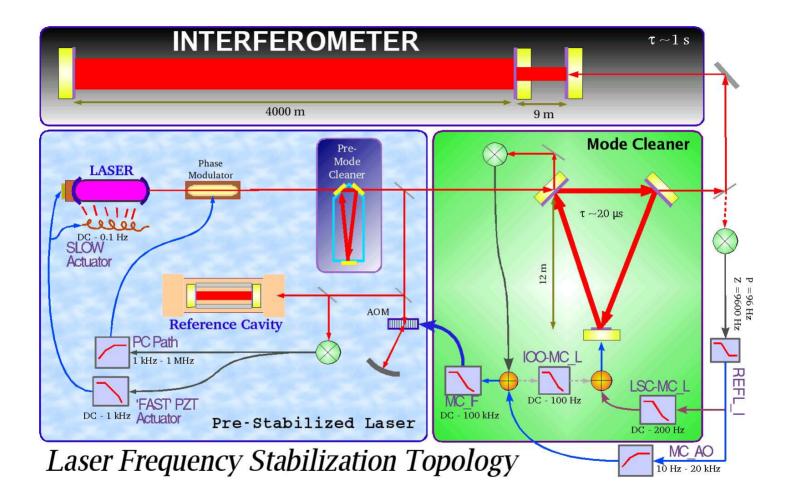
•5 main length loops shown; total ~ 25 degrees of freedom

•Operating points held to about 0.001 Å, .01 µrad RMS

•Typ. loop bandwidths from ~ few Hz (angles) to > 10 kHz (laser wavelength)



Rana Adhikari



Rana Adhikari

Physical Environment Monitoring

• Seismic motion

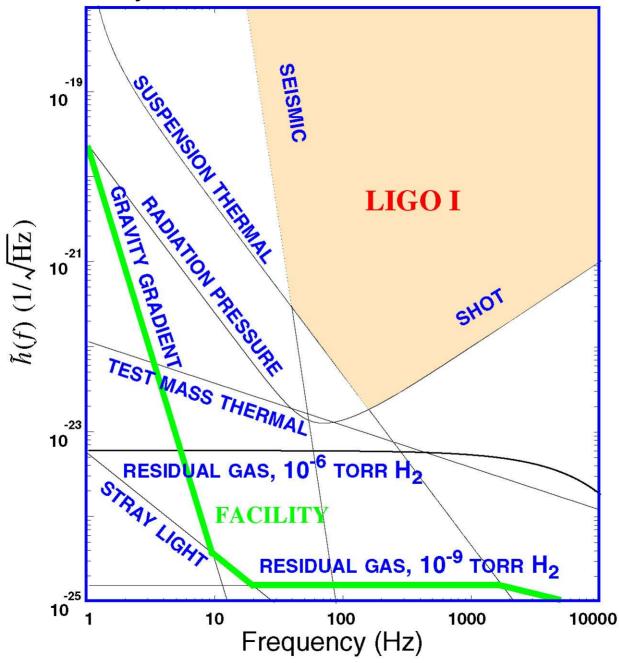
- xyz seismometer/building
- Motion of test mass chambers
 - xyz accelerometers/chamber
- Acoustic excitation
 - microphone/building
- Magnetic fields
 - xyz magnetometer/building
 - xyz high sensitivity coil/site
- Radio Frequency interference
 - multiband 30kHz -100MHz receiver/site
- Main AC power monitor
 - 3 phase monitor/building
- Muon shower detector
 - scintillator-PM tube/site

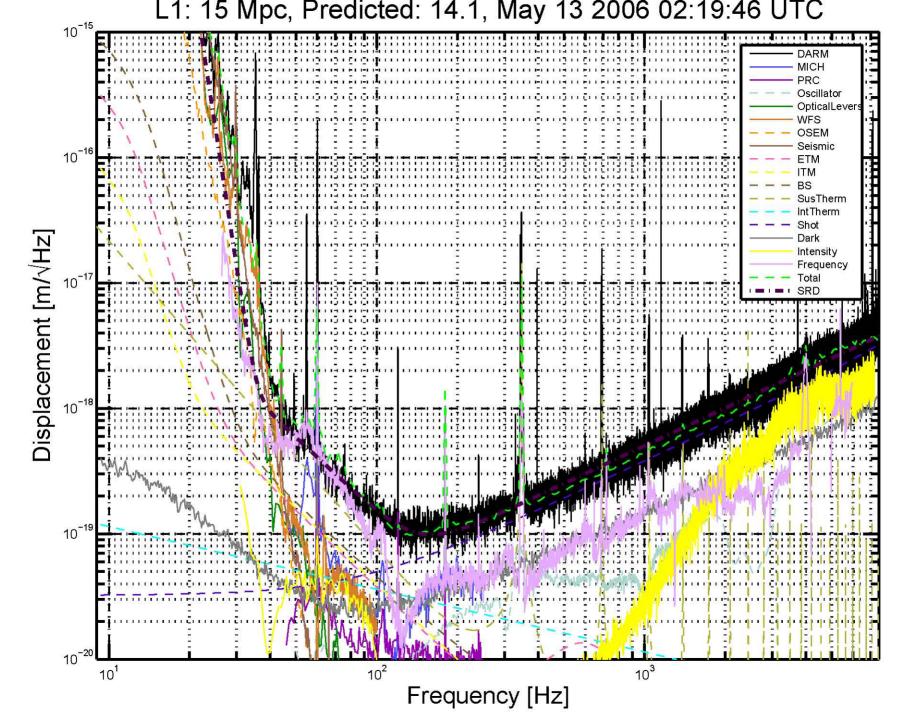
Data channels / Interferometer

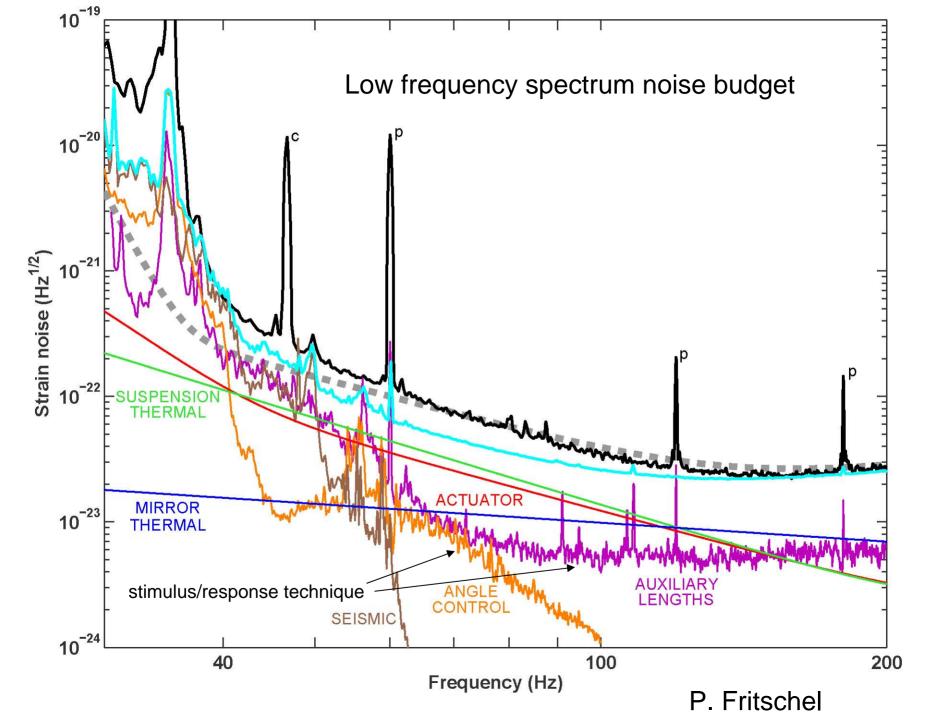
Full data on tape Reduced data on disk

Number of channels	Number of channels	Sample rate/sec
1		262144
46	7	16384
	8	8192
	22	4096
171	82	2048
	5	1024
	96	512
415	7	256
2	43	64
3		32
8391	116	16
1.6M	0.5M	

Mostly idealized and fundamental noise



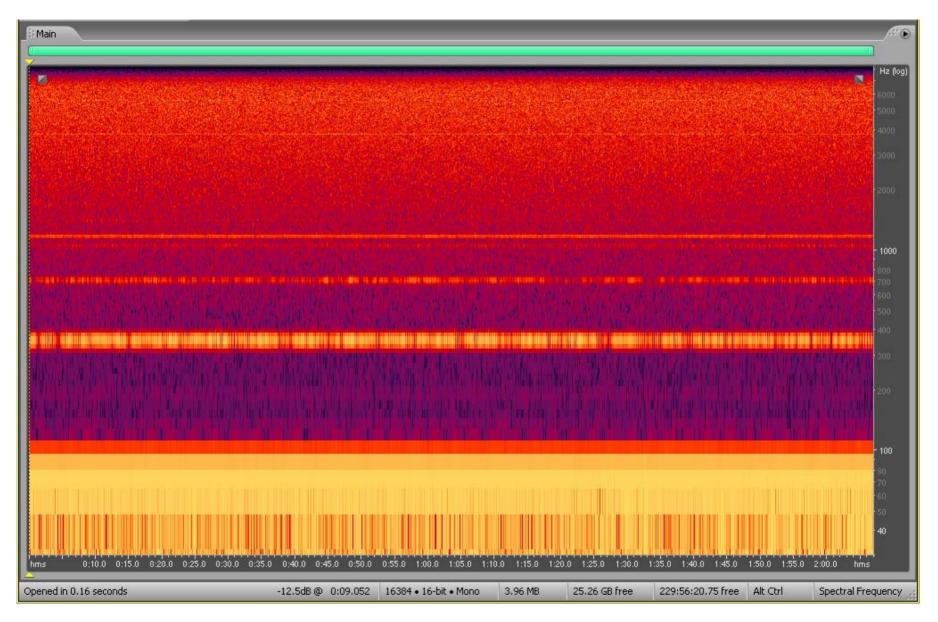




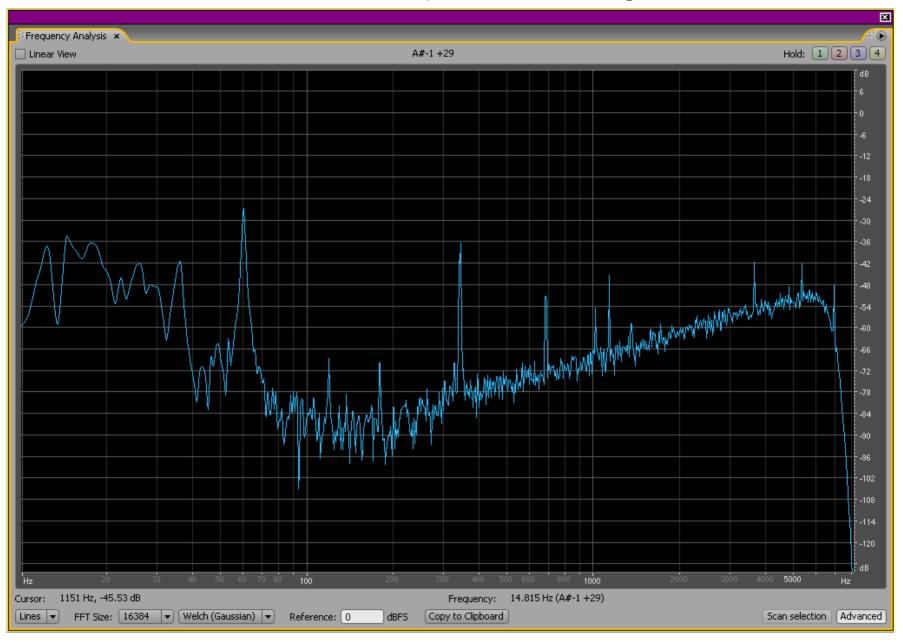
L1 Differential Arm Signal during S5

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L1 differential arm signal spectrum vs time



L1 differential arm spectrum during S5

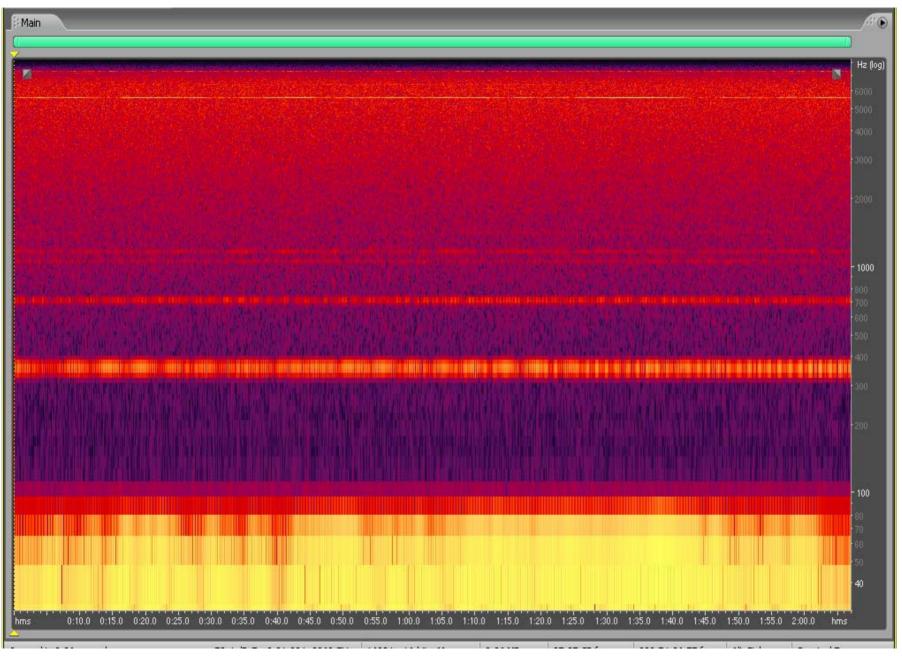


H1 differential arm signal during S5

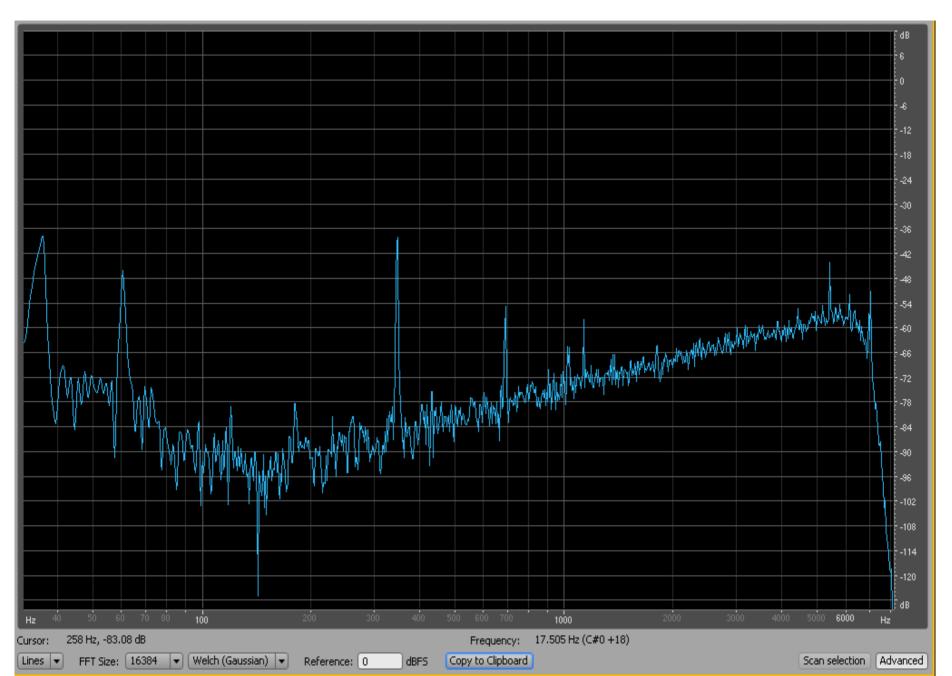


H1 differential arm spectrum vs time in S5



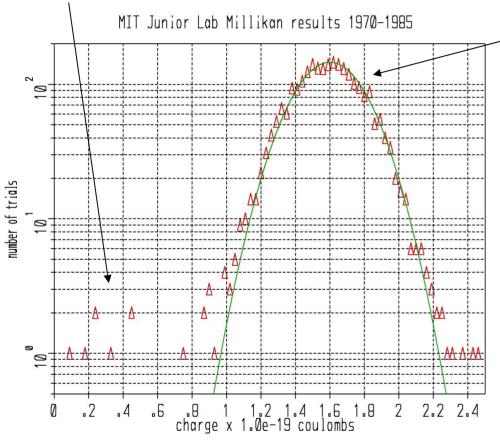


H1 differential arm spectrum in S5



Styles of Experiment

Quarks?

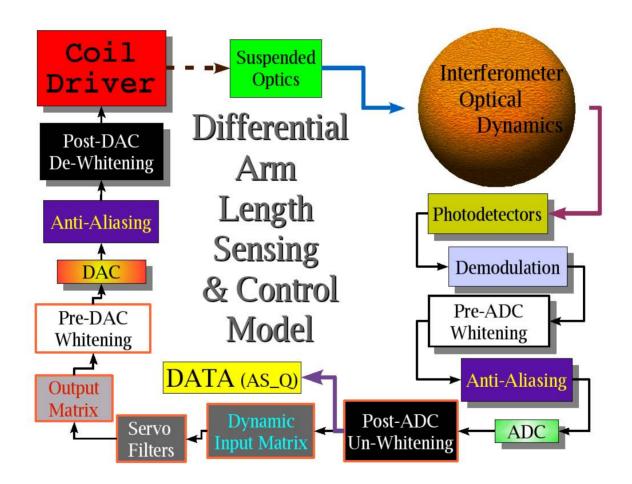


almost Gaussian with variance 0.2, avg 1.6

The tails with their outliers can be neglected in this data – they represent poor control of the experiment parameters. *May also be true in LIGO but unfortunately the tail contains the signal.*

MIT Junior Physics Laboratory 15 year history with the Millikan oil drop experiment

CALIBRATION



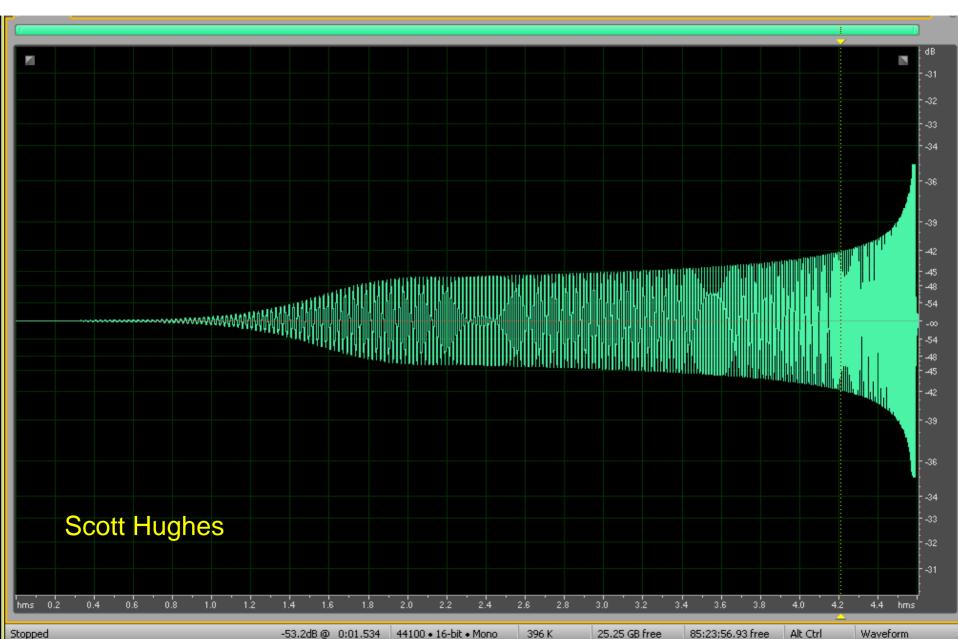
Rana Adhikari

VETOES

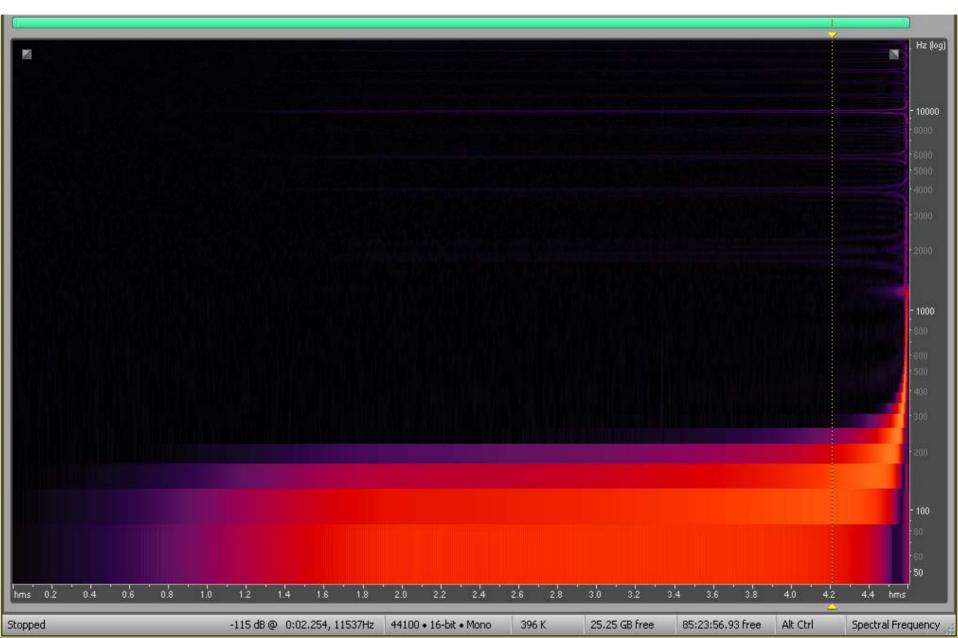
- Interferometer subsystem and physical environment monitor signals decide data quality
 - statistical correlation to GW channel
 - stimulus/response measurement to GW channel
 - need to establish veto does not eliminate GW
 - need to determine effectiveness/duty cycle loss
- Highly interactive procedures with results that change with state of the instrument
- Still learning how to do this

5 solar mass BH binary inspiral

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5 solar mass BH inspiral spectrum vs time

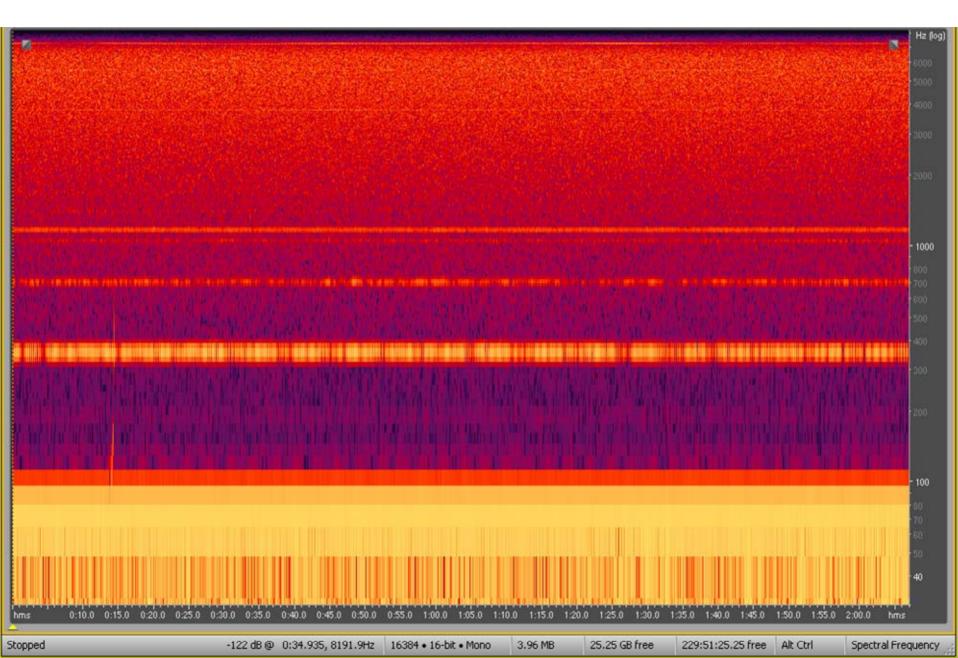


5 solar mass BH inspiral at 20Mpc in VIRGO measured in S5 at L1

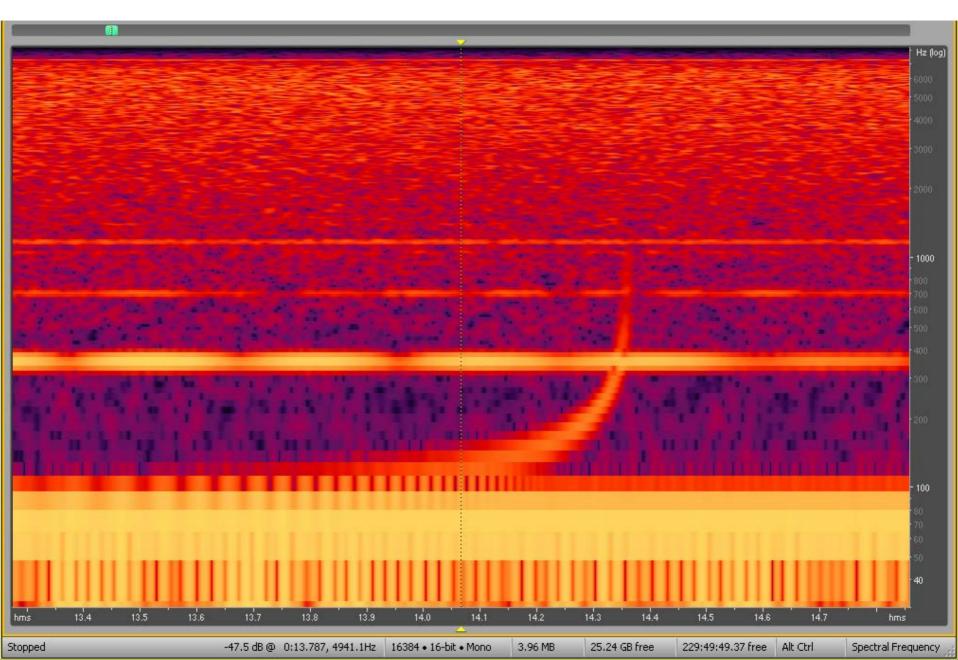


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Spectrum vs time of 5 solar mass BH inspiral at 20Mpc VIRGO in S5 in L1



Enlargement of time axis of the previous slide



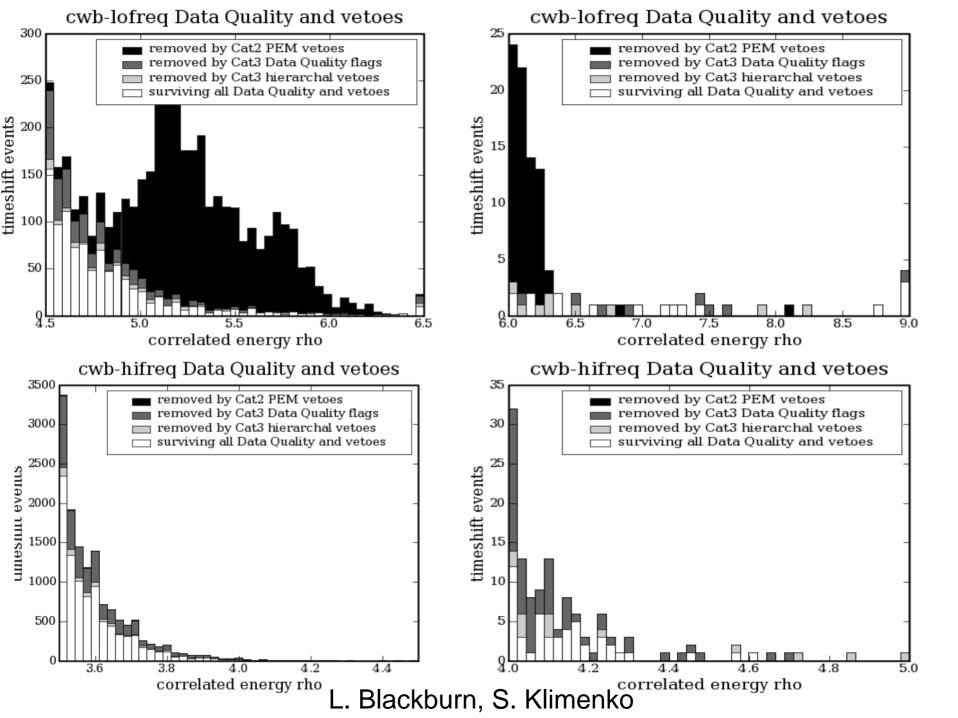
NS/NS binary inspiral triggers in the year 1 of S5 in L1 and H1

L1 single interferometer clusters of triggers L1Clusters L1Clusters after cat2/3 auto vetoes L1after cat 2/3 to-be-auto vetoes L1Clusters after cat2/3 unclaimed vetoes 3 log10(Number)) S 10^2 10 10^3 10^4 SNR

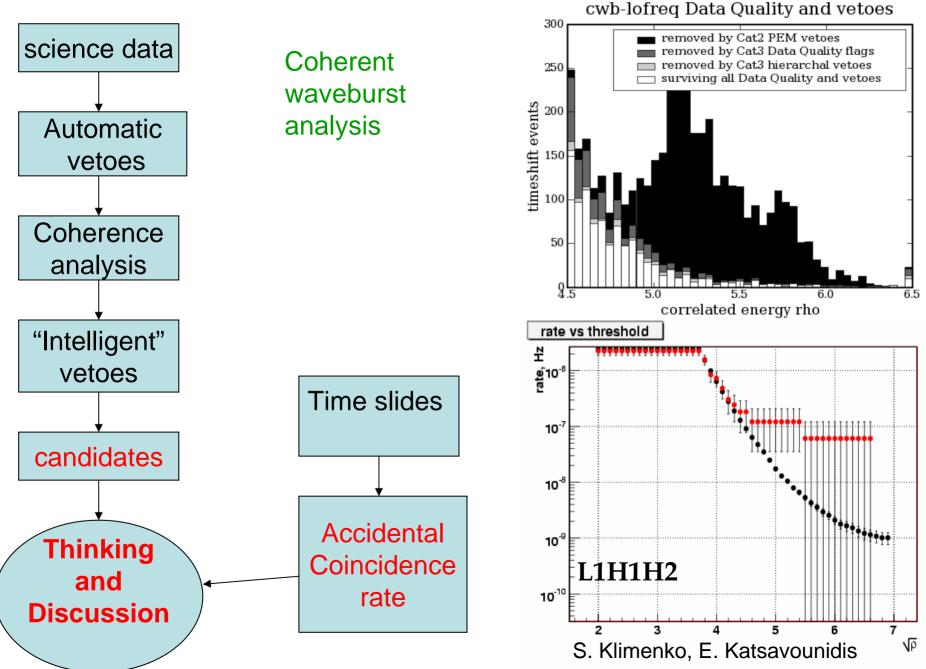
H1Clusters H1Clusters after cat2/3 auto vetoes H1after cat 2/3 to-be-auto vetoes H1Clusters after cat2/3 unclaimed vetoes 3 log10(Number)) 2 10^2 10^4 10 10^3 SNR

H1 single interferometer clusters of triggers

Jake Slutsky LSU



Coincidence rate estimation



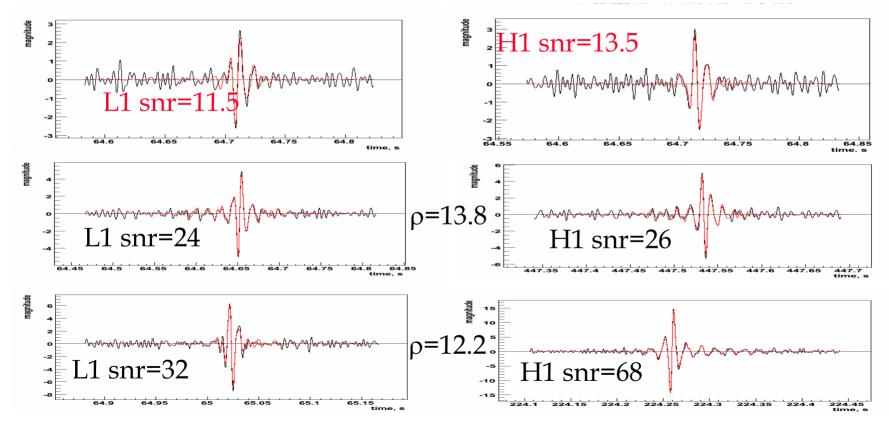
Constant background (L1H1H2) in S5

• S5 events reconstructed by cWB

-black - bandlimited detector responses

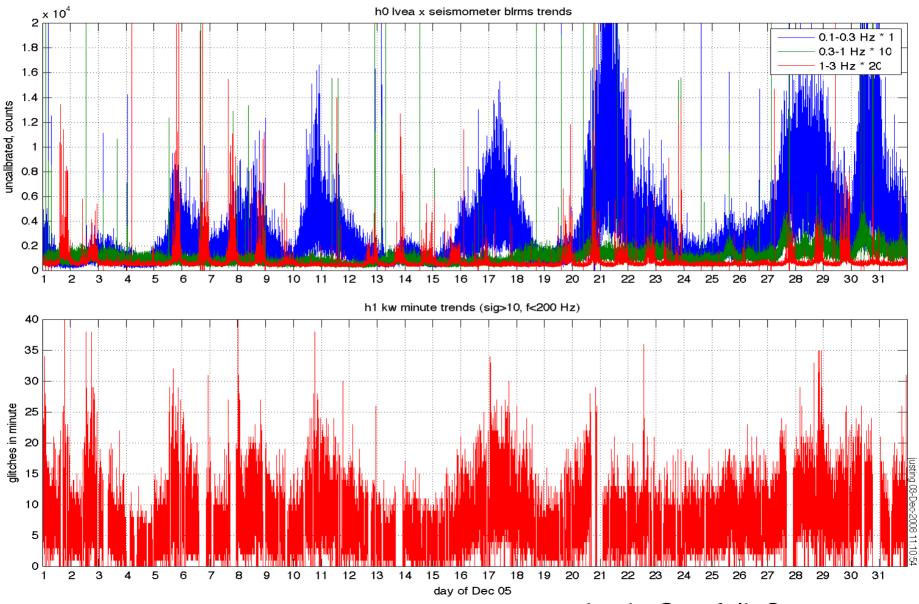
–red – reconstructed responses as if produced by a common GW signal

• Pass the coherence test



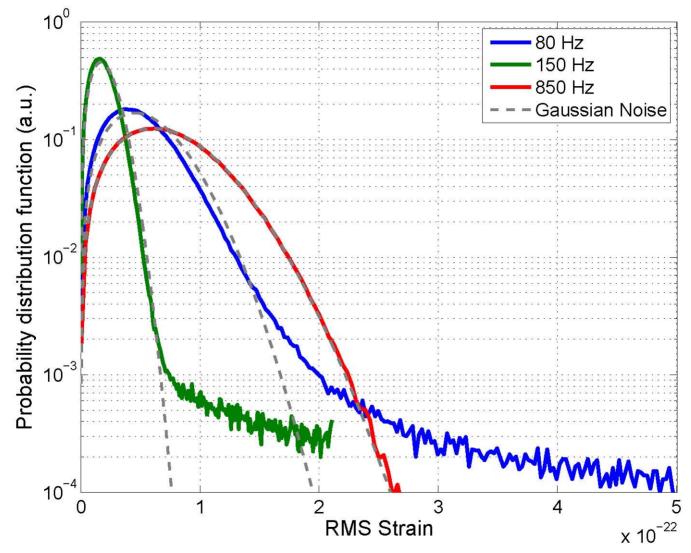
S. Klimenko. Univ of Florida

Up-Conversion: Seismic noise to pulses few oscillations at ~100Hz



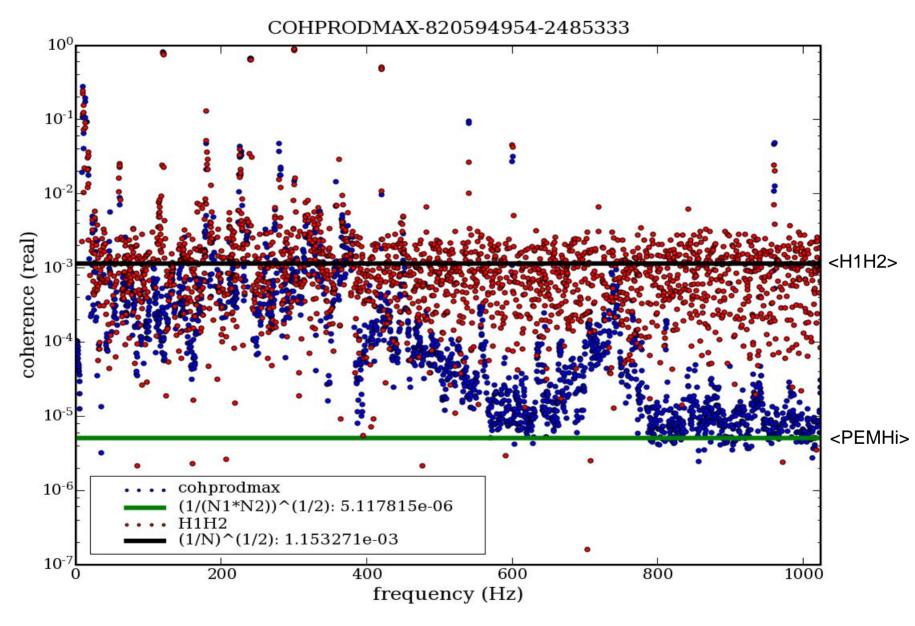
Justin Garofoli Syracuse

Rayleigh Distribution in Narrow Frequency Bands



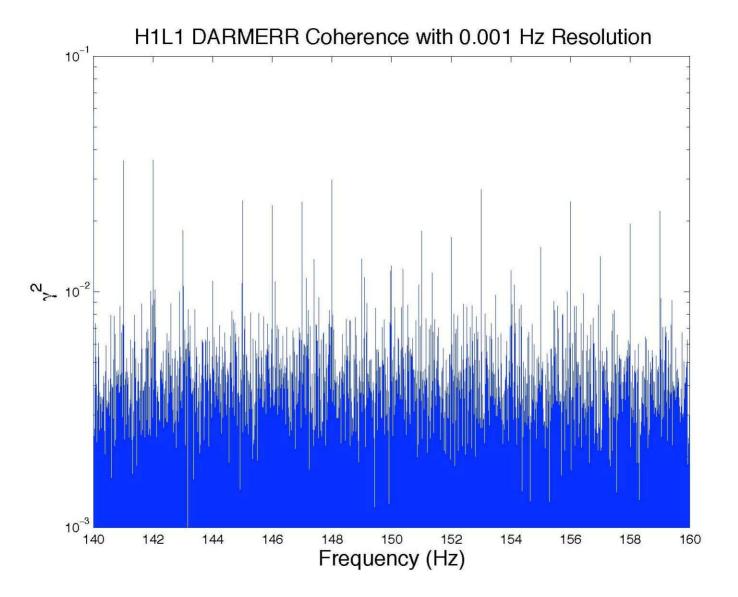
Sam Waldman

Coherence between H1,H2 and PEM vs Frequency



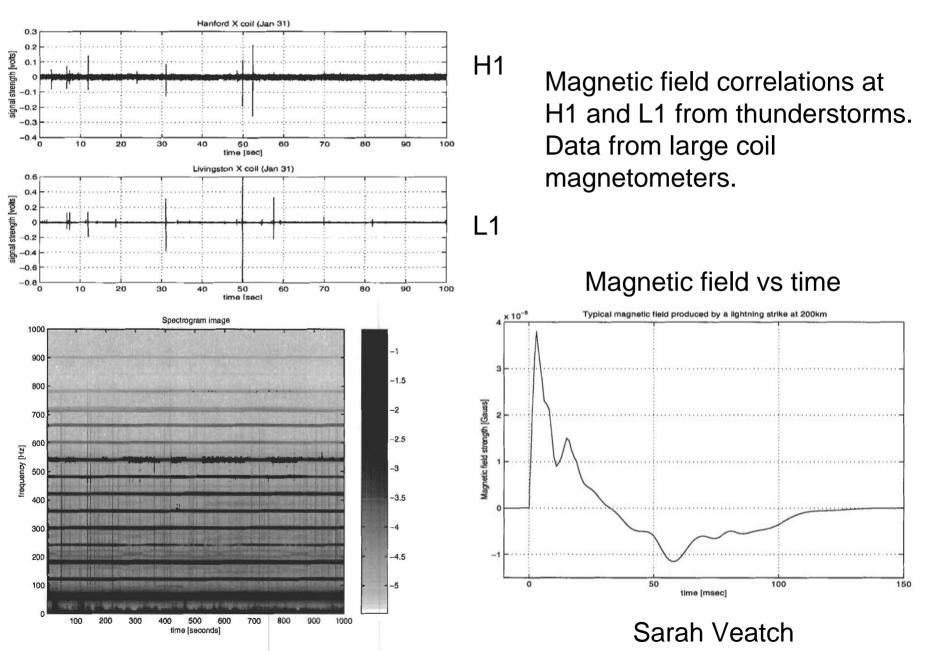
Nelson Christensen, Carleton College

Coherence between L1 and H1 vs Frequency



Vuc Mandic Univ of Minnesota

Magnetic pulses at H1 and L1: Lightning



Last words

- David Reitze and Maria Alessandra Papa show some interesting results despite what I have told you.
- The combined efforts of the data analysts and the instrument commissioners are the way to reduce the non-Gaussian and nonstationery behaviour of the instrument.